

# Neural Network Nearest-Neighbour Transformation for Segmentation of Retinal Blood Vessels

## Bachelor's Thesis Final Talk

Anne-Marie Strauch

Supervisors: Lennart Husvogt, Tino Haderlein, Andreas Maier

28.11.2016

Pattern Recognition Lab (CS 5)



FRIEDRICH-ALEXANDER  
UNIVERSITÄT  
ERLANGEN-NÜRNBERG

TECHNISCHE FAKULTÄT

# Outline

- Introduction
- Approach
  - Training
  - Testing
- Experiments
- Discussion
- Conclusion and Outlook



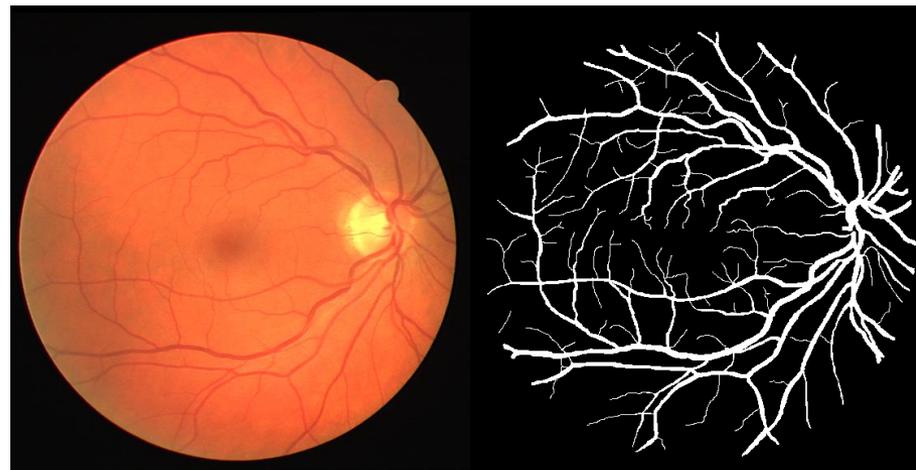
# Outline

- **Introduction**
- Approach
  - Training
  - Testing
- Experiments
- Discussion
- Conclusion and Outlook



## Fundus Photography

- non-invasive modality for examining eye
- diagnosis of glaucoma, diabetic retinopathy, ...
  - diabetic retinopathy leading cause for acquired blindness
- segmentation supports computer-aided diagnosis



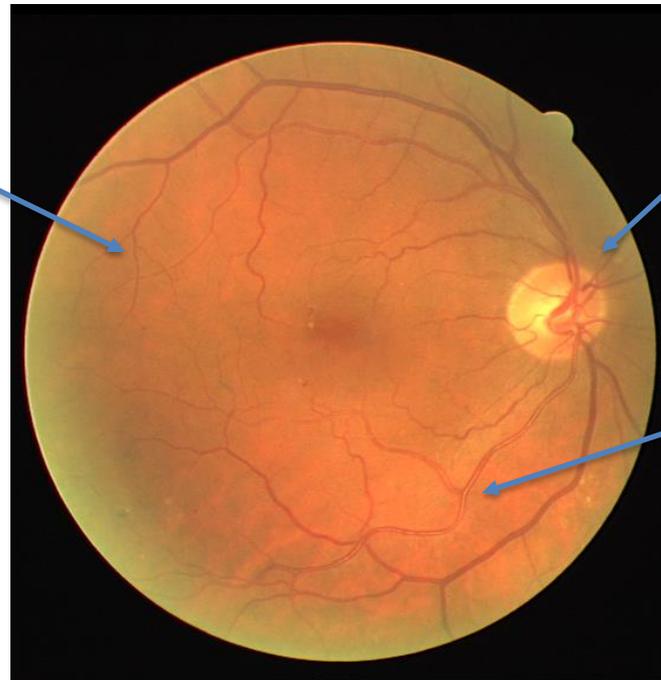
Fundus image and segmentation [DRIVE database]



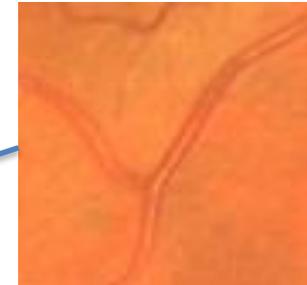
## Some challenges

thin vessels

- bifurcations
- lighting variations
- poor contrast
- pathologies



bright optic disc



central vessel  
reflex



# Introduction

---

## $N^4$ -Fields: Neural Network Nearest Neighbor Fields for Image Transforms

---

Yaroslav Ganin, Victor Lempitsky  
Skolkovo Institute of Science and Technology (Skoltech)

- reimplementation of  $N^4$  Paper
- experiments with varying parameters
- evaluation on DRIVE database

# Outline

- Introduction
- **Approach**
  - Training
  - Testing
- Experiments
- Discussion
- Conclusion and Outlook





## N<sup>4</sup>-Fields

---

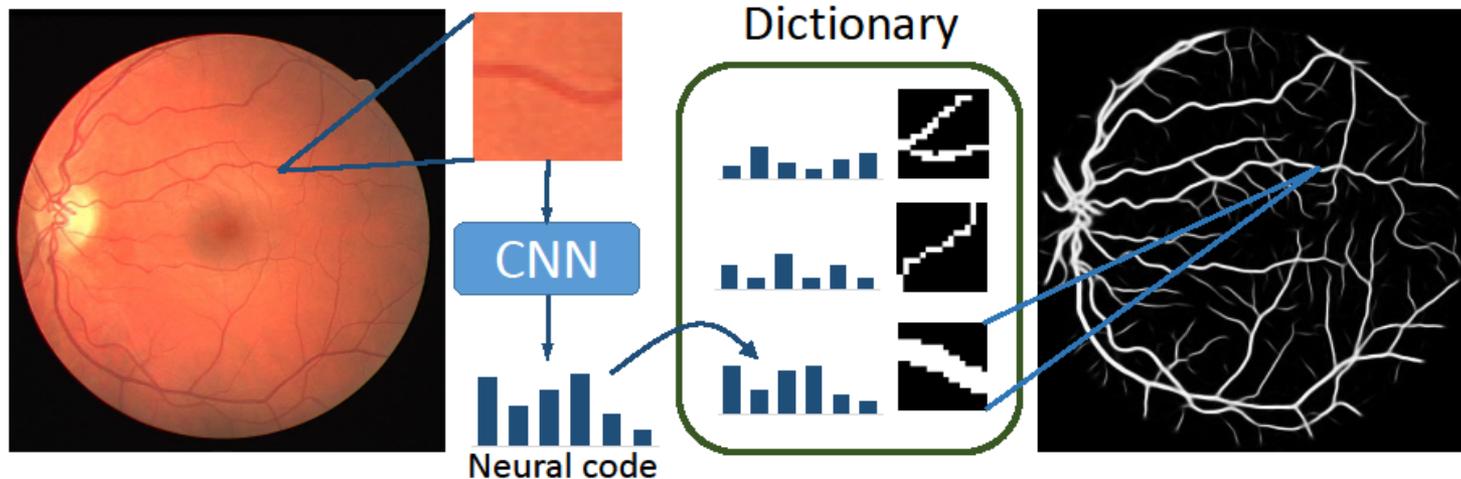
### ***N*<sup>4</sup>-Fields: Neural Network Nearest Neighbor Fields for Image Transforms**

---

Yaroslav Ganin, Victor Lempitsky  
Skolkovo Institute of Science and Technology (Skoltech)

- architecture for natural edge detection/thin object segmentation
- neural network and nearest-neighbour search applied sequentially
- process images patch-by-patch

## N<sup>4</sup>-Fields



- run patch through convolutional neural network  
→ receive neural code
- map to closest dictionary entry using nearest-neighbour classifier  
→ retrieve output patch
- average all output patches to segment image

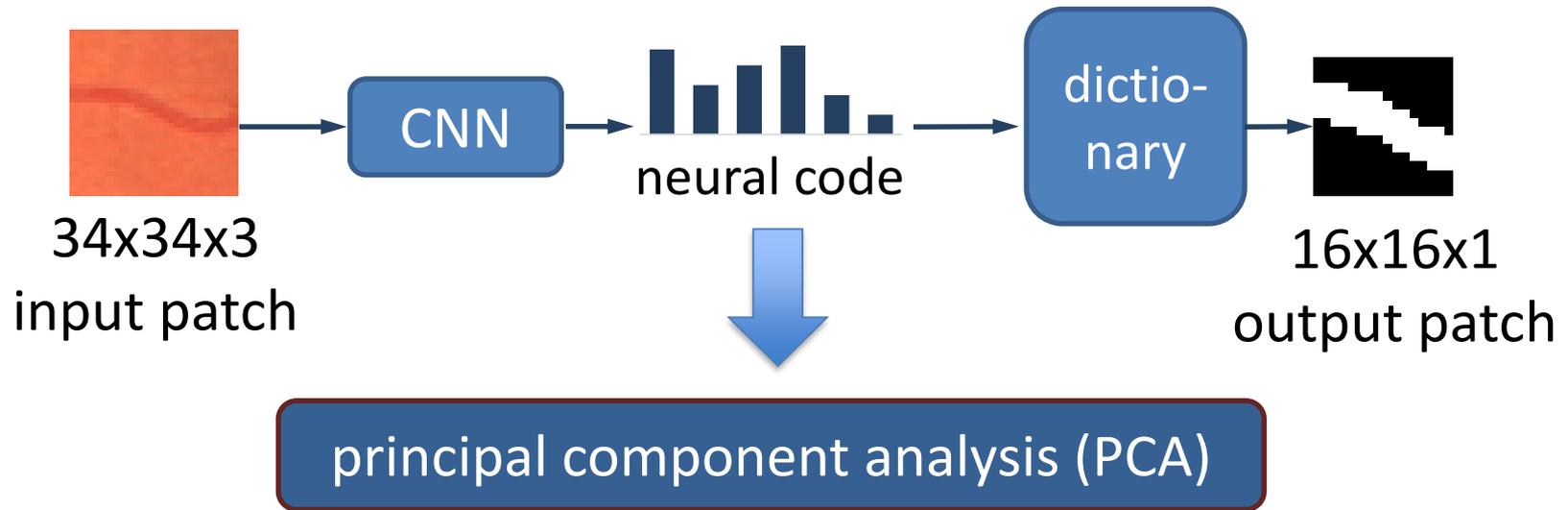
# Outline

- Introduction
- Approach
  - **Training**
  - Testing
- Experiments
- Discussion
- Conclusion and Outlook





## Training

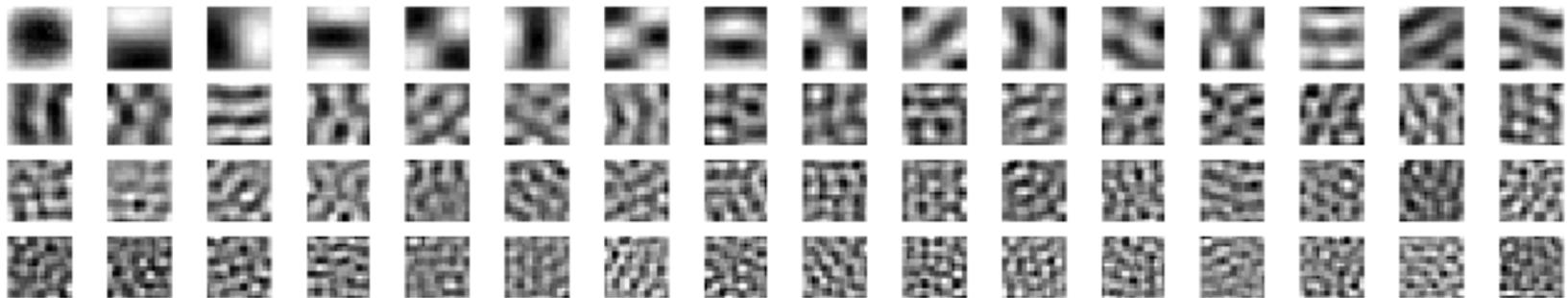


neural code length  
→ number of eigenvectors used  
in data reduction

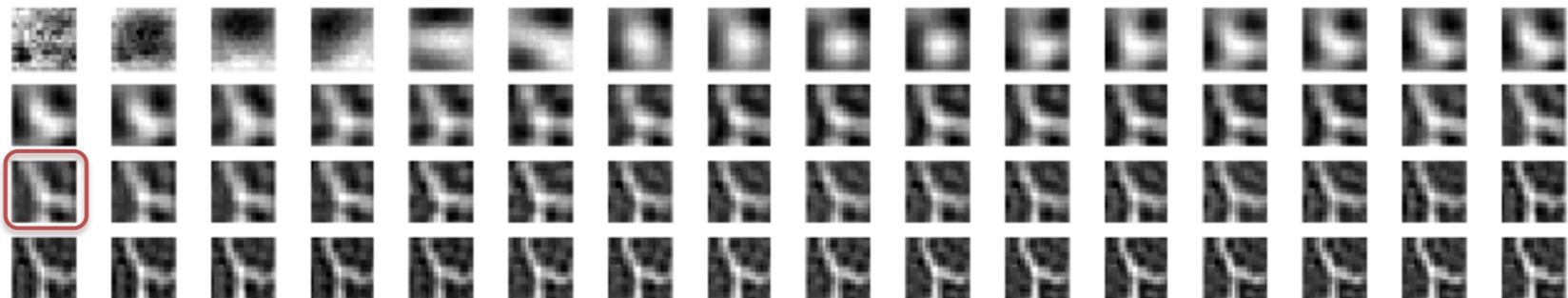
$$\mathbf{X} = \begin{bmatrix} \text{patch 1} \\ \text{patch 2} \\ \vdots \\ \text{patch N} \end{bmatrix}$$



# PCA



first 64 eigenvectors



reconstruction of a patch with a total of 63 eigenvectors





# Convolutional Neural Network

#	Layer type	#filters/units	Filter size	Output size
1	convolutional + ReLU +max-pooling	96	7x7	28x28x96
		-	2x2	14x14x96
2	convolutional + ReLU + max-pooling	128	5x5	10x10x128
		-	2x2	5x5x128
3	convolutional + ReLU	256	3x3	3x3x256
4	fully connected + ReLU	768	-	768
5	fully connected + ReLU	768	-	768
6	fully connected + linear	16	-	16

max-pooling:

6	3
9	12

ReLU:  $\varphi(x) = \max(0, x)$

linear:  $\varphi(x) = x$



## Convolutional Neural Network

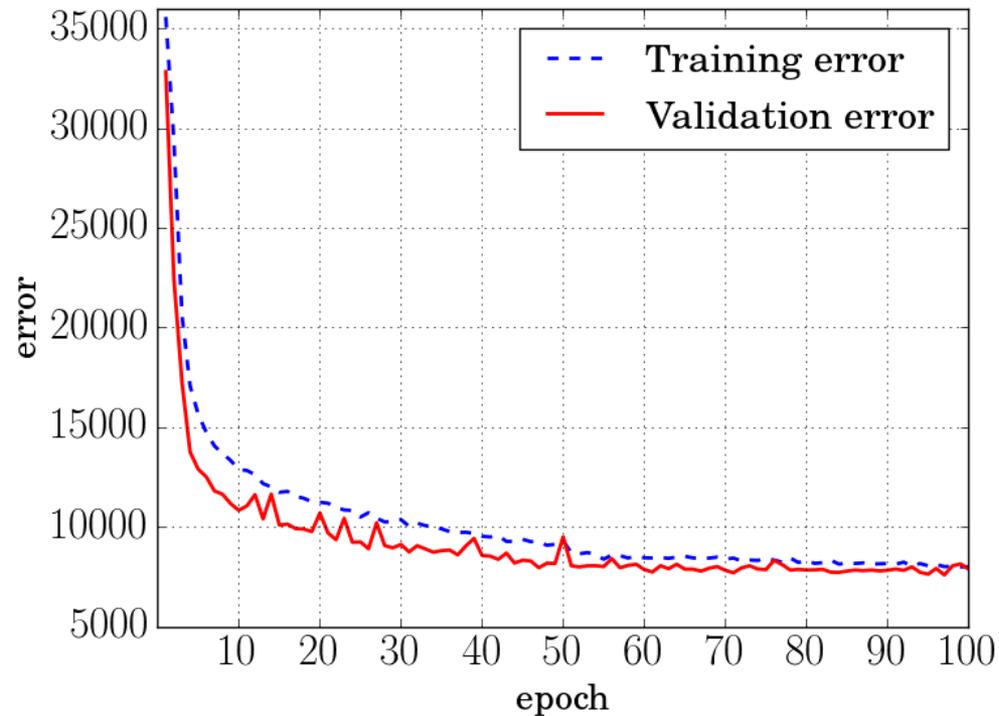
- dropout with 50 %
- update rule Adadelta → parameter-wise learning rate
- input patches drawn at random locations with random rotations
- loss function:

$$L = \frac{1}{b \cdot f} \sum_{i=1}^b (\text{CNN}(P; W)_i - \text{PCA}(\mathbf{A}(P))_i)^T \cdot (\text{CNN}(P; W)_i - \text{PCA}(\mathbf{A}(P))_i)$$



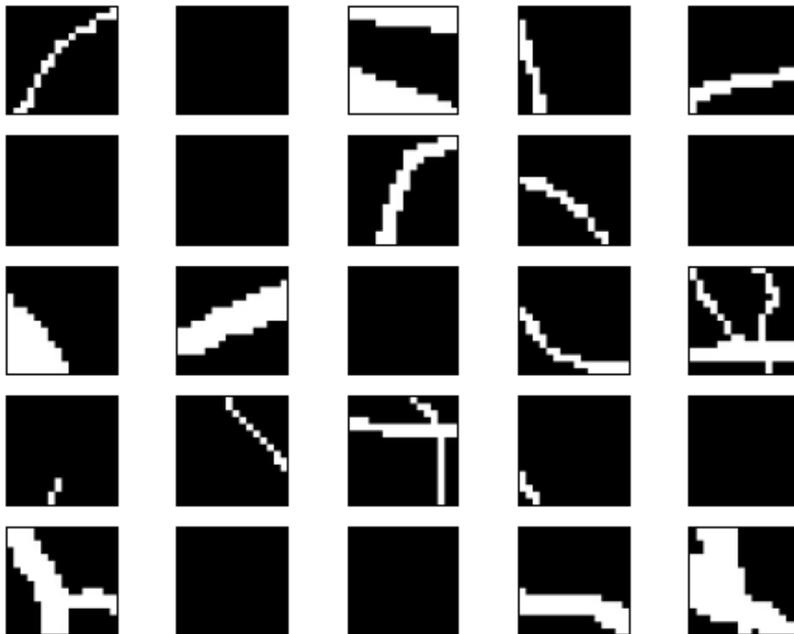
## CNN Training Time

- about 80 epochs per model  
→ 90 to 120 minutes training

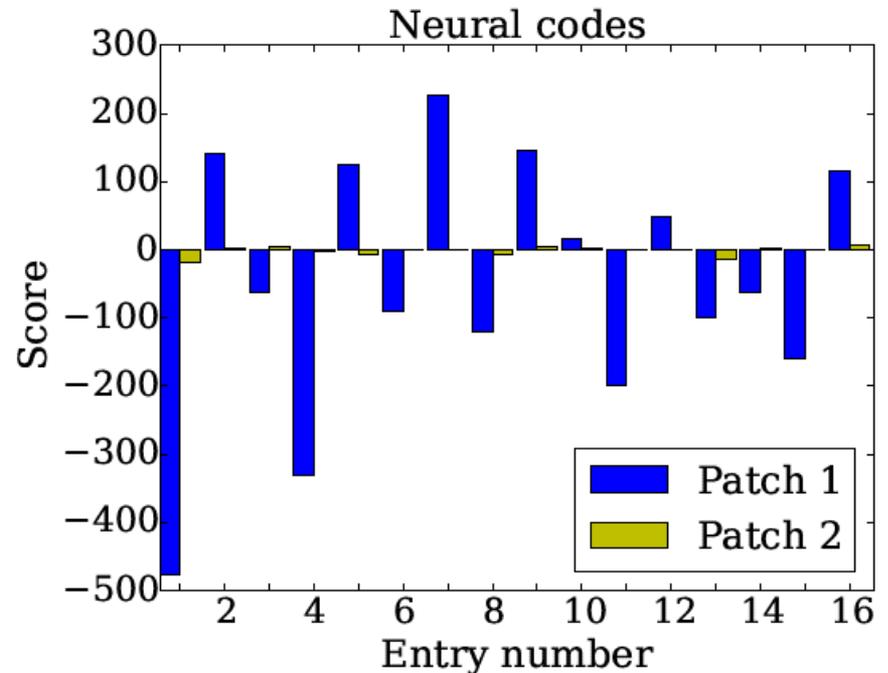


# Dictionary

- retrieve neural codes from randomly sampled patches
- set nearest-neighbour classifier



example entries from dictionary



neural codes

# Outline

- Introduction
- Approach
  - Training
  - **Testing**
- Experiments
- Discussion
- Conclusion and Outlook





## Testing

- not patches but whole images
  - re-implement fully connected layers as convolutional
  - average over all output patches
- output is soft classification

# Outline

- Introduction
- Approach
  - Training
  - Testing
- **Experiments**
- Discussion
- Conclusion and Outlook





## Experiments

- on DRIVE database
- soft classification has to be thresholded
- → simple thresholding that maximizes average accuracy

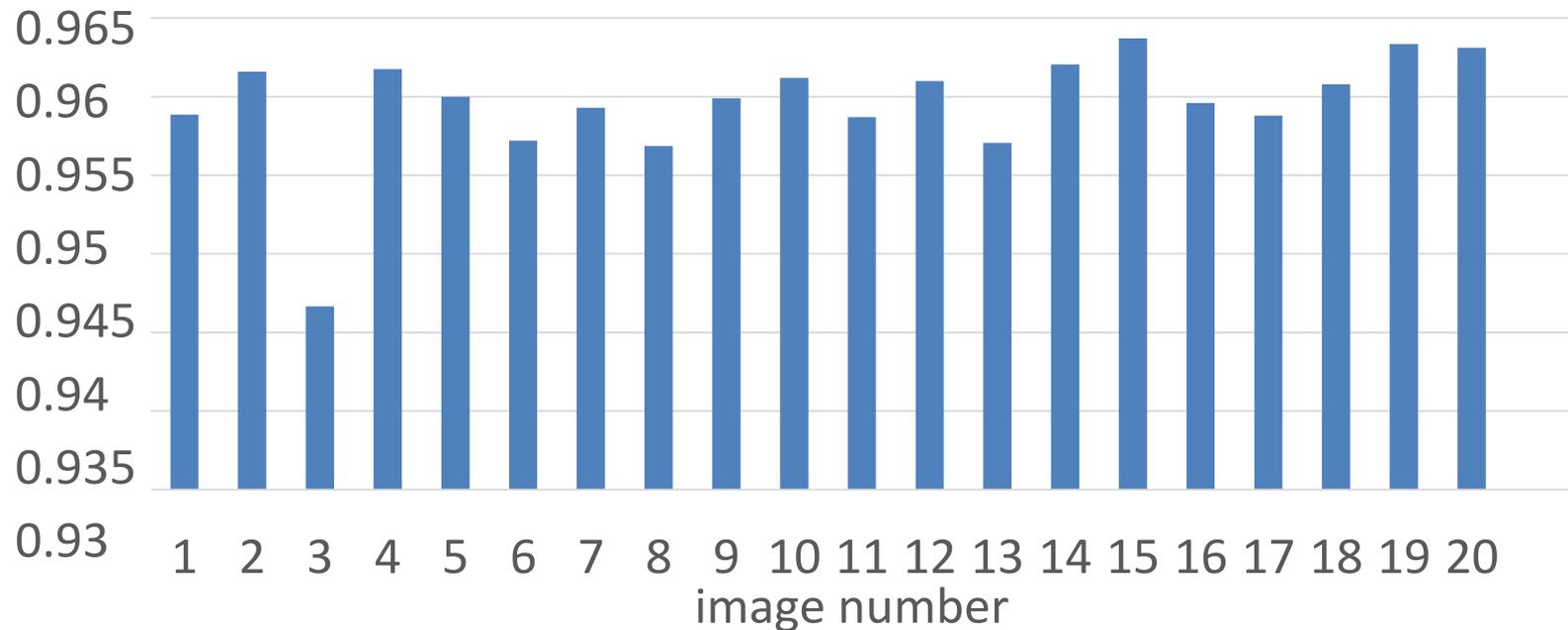
### **Trials:**

- neural code length
- dictionary size
- multi-resolution
- normalized neural codes
- green colour channel only
- ensemble of multiple models



## Original N<sup>4</sup> Settings

accuracy

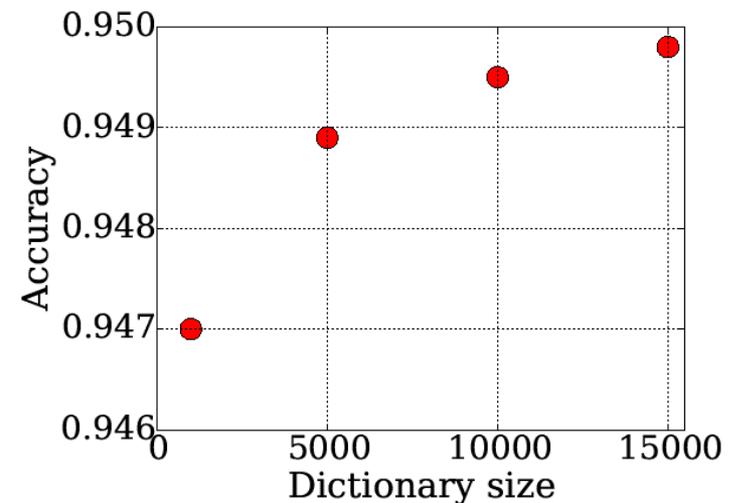


- neural code length = 16, dictionary size = 10000
- mean accuracy of 0.9491
- mean F1 score of 0.7844 (N<sup>4</sup> paper: 0.81)



## Dictionary Size

dictionary entries	accuracy
1000	0.9470
5000	0.9489
<b>10000</b>	<b>0.9495</b>
15000	0.9498



- increase in performance with growing dictionary size
- problem with long runtime for very large dictionaries



## Neural Code Length

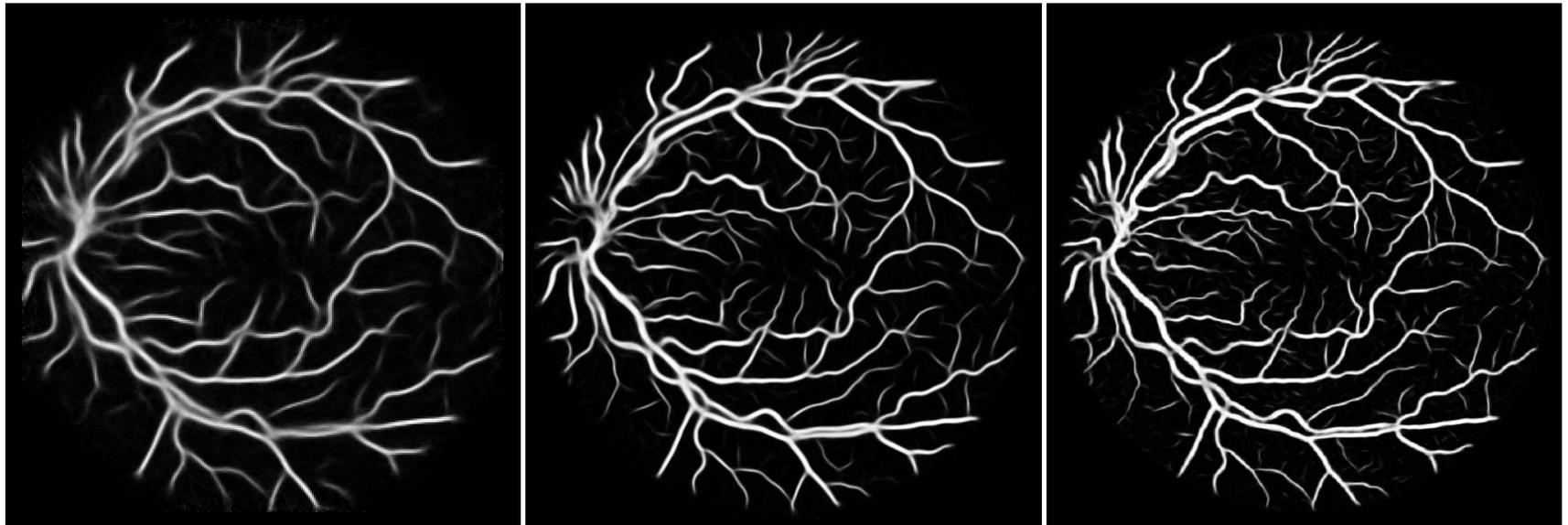
neural code length	final test error	accuracy
16	11241	0.9491
24	8600	0.9476
<b>32</b>	<b>8159</b>	<b>0.9495</b>
40	7502	0.9489

- test error for CNN decreases but no increase in performance
- 32 works well in other experiments



## Multiple Scales

- train CNN on all 3 scales
- process input with 3 different resolutions each
- result: normal + 1.8 resolution (accuracy = 0.9506)



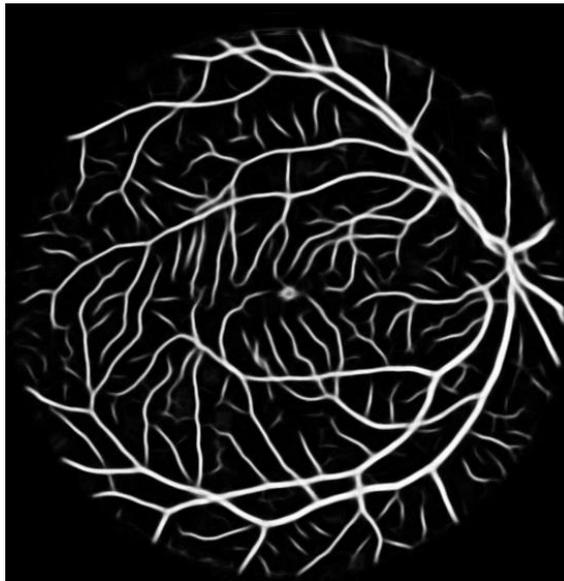
half resolution

normal resolution

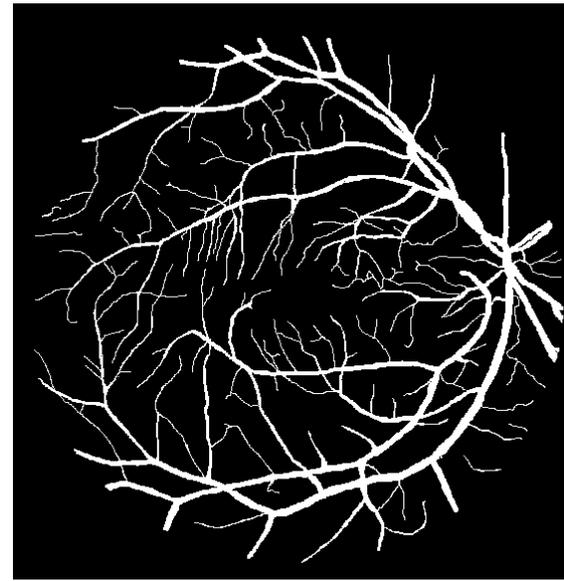
1.8 resolution

## Normalized Neural Codes

- normalize neural codes in dictionary and from CNN
- accuracy = 0.9459 (unnormalized = 0.9495)
- many false positives, but thin vessels recognized



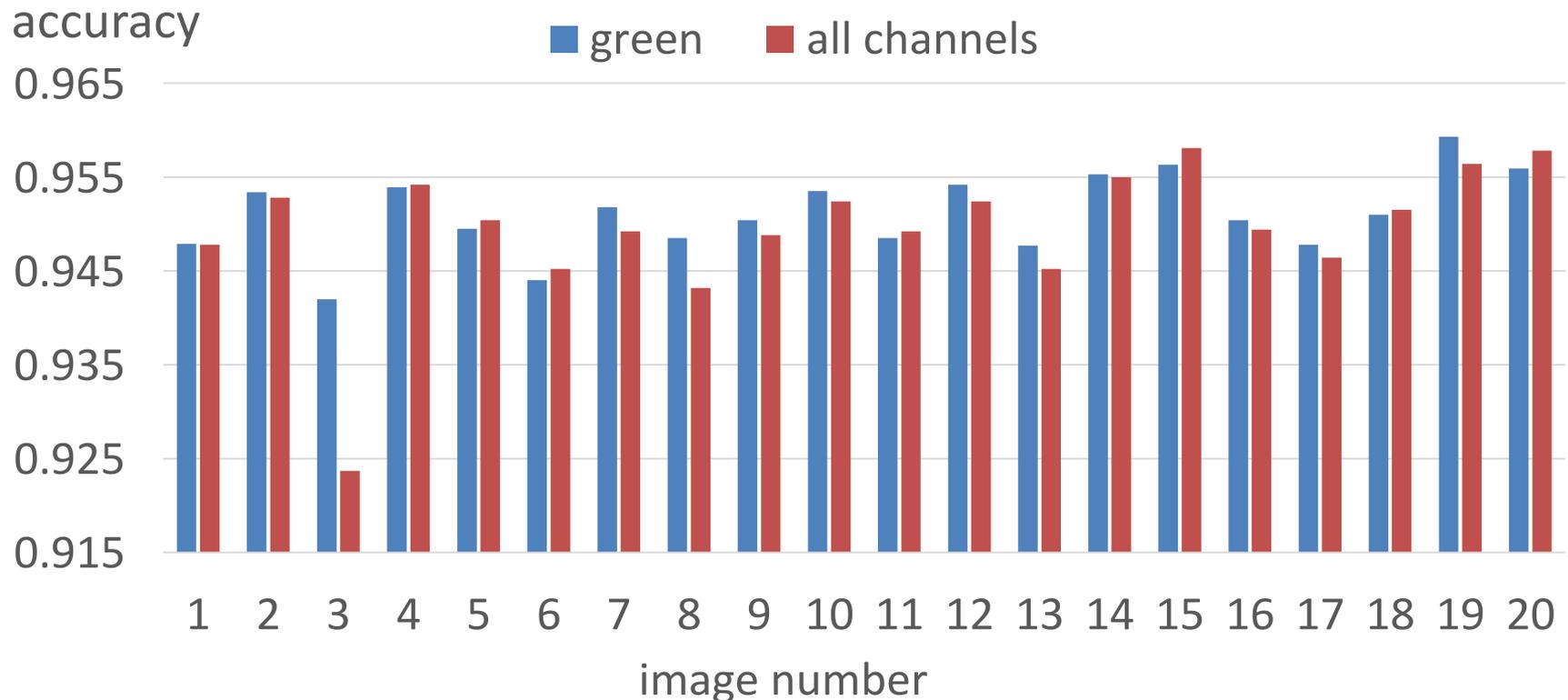
segmentation



ground truth



## Green Colour Channel Only



- mean accuracy green: 0.9511



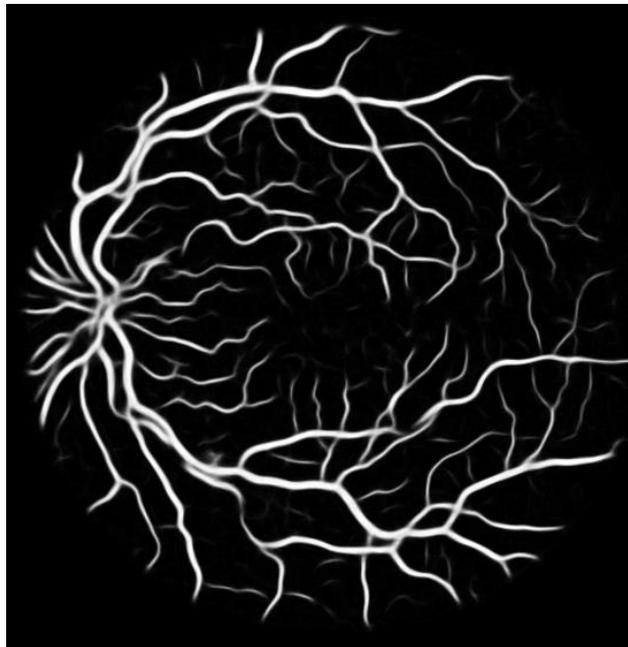
**overall best model**

- mean accuracy all channels: 0.9495

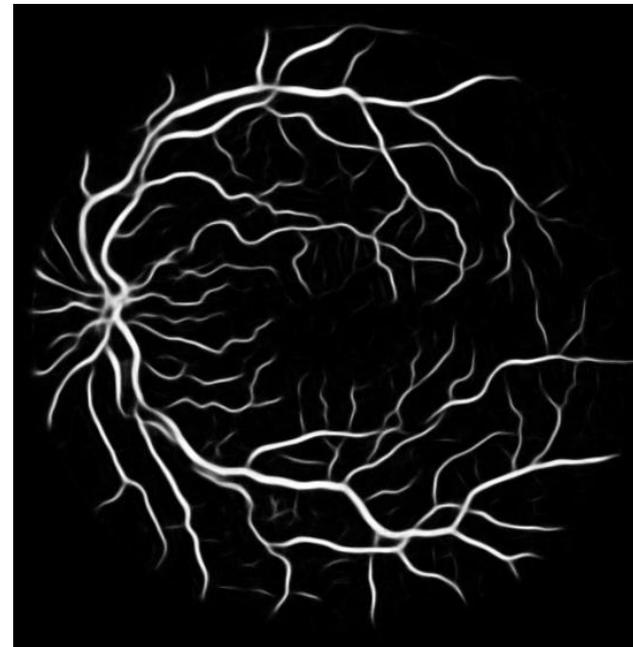


## Green Channel Only

$$\Delta_{accuracy} = 0.0183$$



green  
accuracy = 0.942



all channels  
accuracy = 0.9237



## Ensemble

- combine output of multiple models
  - *green, 15000, 1.8* and *norm* (accuracy = 0.9521)
- adding more models does not necessarily increase performance
- disadvantage: long runtime, 4 CNNs have to be trained



## Experiments – Summary

model	neural code length	dictionary size	accuracy
original	16	10000	0.9491
dictionary size	32	15000	0.9498
neural code length	32	10000	0.9495
normal + 1.8 resolution	32	10000	0.9506
normalized neural codes	32	10000	0.9459
<b>green channel only</b>	<b>32</b>	<b>10000</b>	<b>0.9511</b>
<b><i>green, 15000, 1.8 and norm</i></b>	<b>32</b>	<b>10000 15000</b>	<b>0.9521</b>

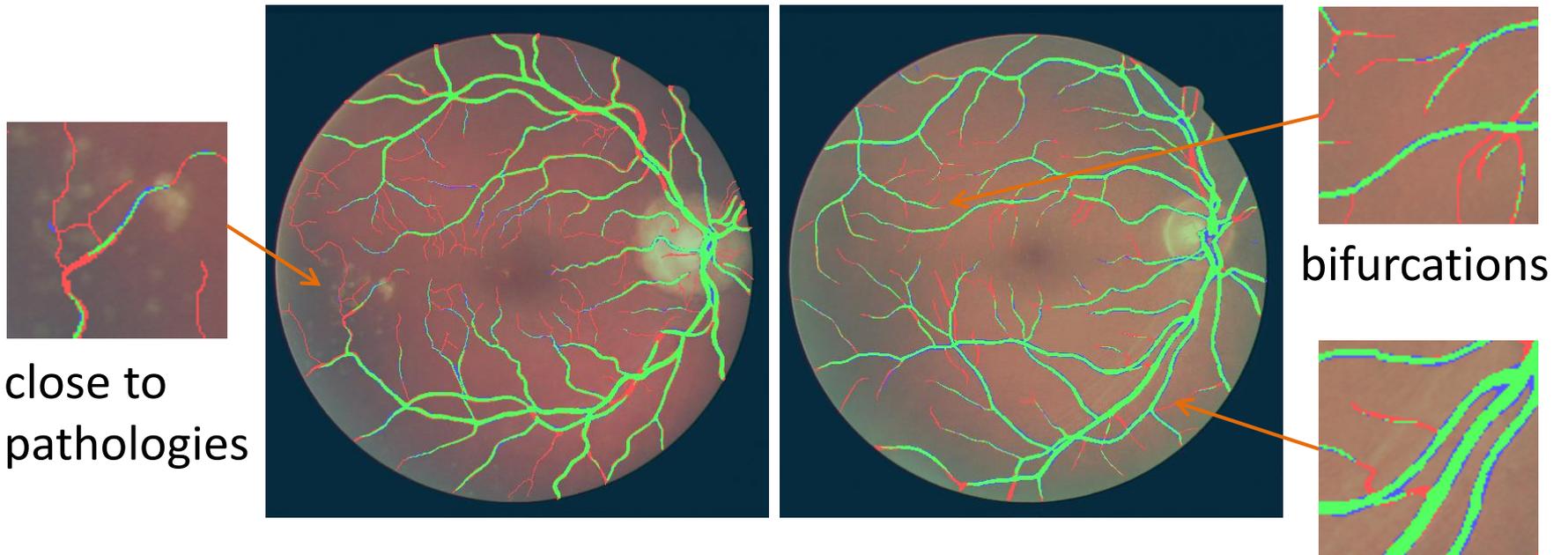
# Outline

- Introduction
- Approach
  - Training
  - Testing
- Experiments
- **Discussion**
- Conclusion and Outlook





## Discussion



close to  
pathologies

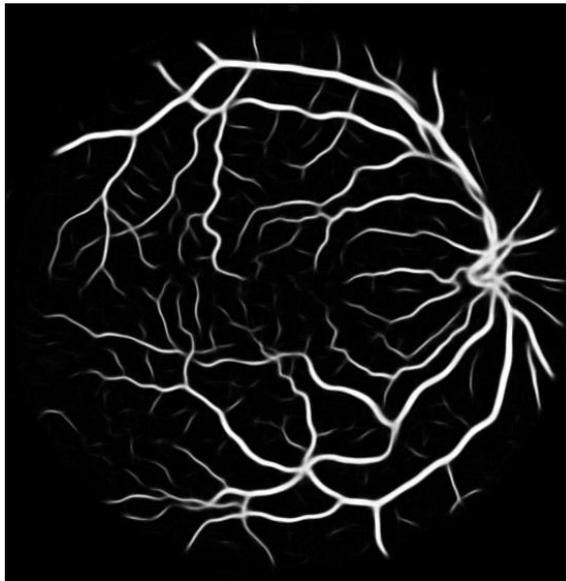
bifurcations

thicker vessels

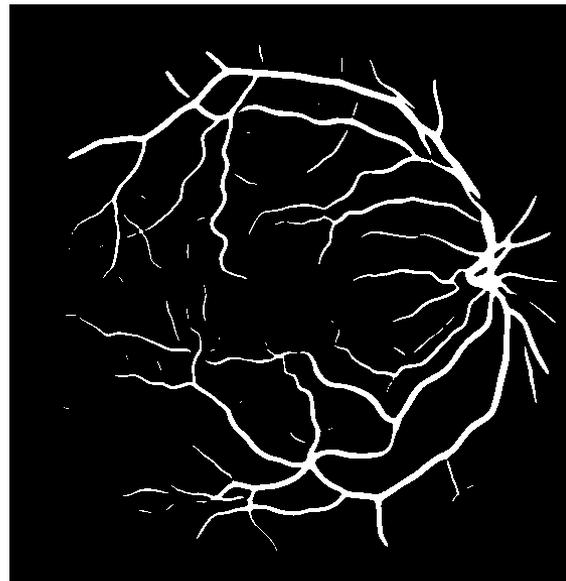
green = true positive  
red = false negative  
blue = false positive

## Discussion - Binarization

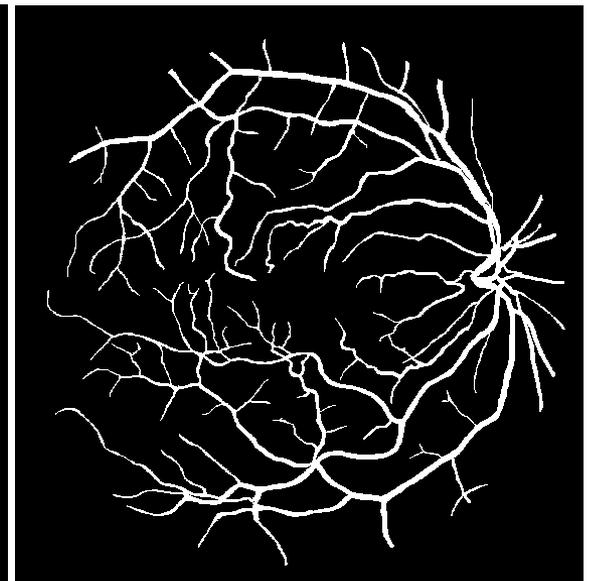
- trade-off between thin vessels and correct vessel thickness



soft classification



binary segmentation



ground truth

# Outline

- Introduction
- Approach
  - Training
  - Testing
- Experiments
- Discussion
- **Conclusion and Outlook**





## Conclusion and Outlook

- average accuracy 0.9511 on DRIVE database
- green colour channel only
- runtime 40 seconds, about 100 minutes training
- for optic disc, central vessel reflex and main vessels good performance
- very thin vessels and bifurcations still challenging
  
- more advanced thresholding technique (hysteresis, adaptive)
- higher resolution images
- reduce runtime
- different internal representation than PCA of patches

**Thank you for your attention!**

