

Structure Tensor

As explained in the lecture

$$J = \begin{pmatrix} f_x^2 & f_x f_y \\ f_x f_y & f_y^2 \end{pmatrix}$$

J has always rank 1

$$\lambda_1 \gg \lambda_2 = 0$$

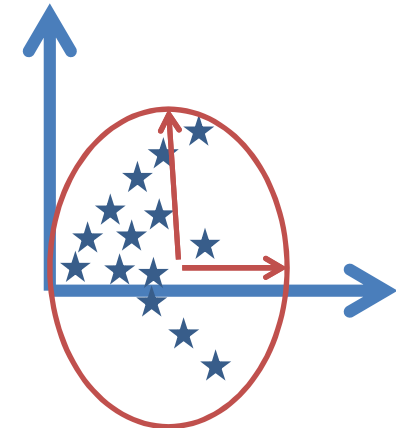
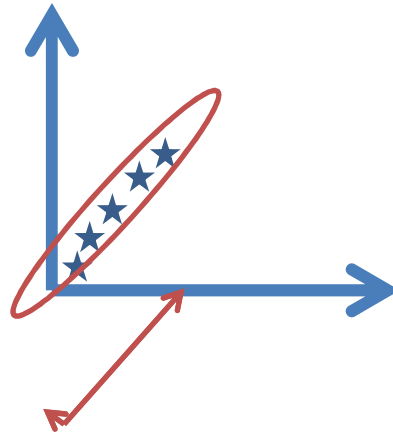
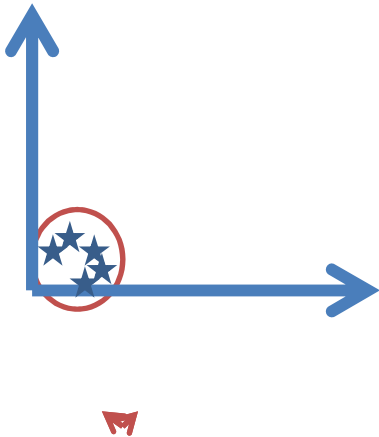
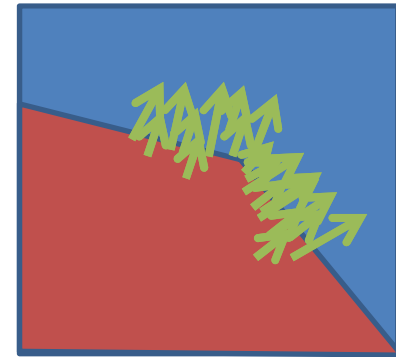
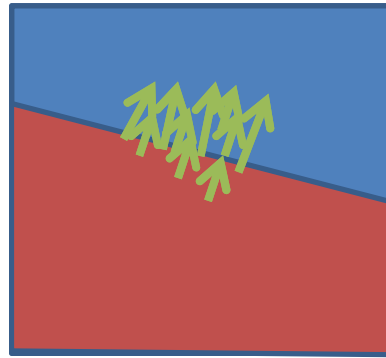
⇒ We need a spatial averaging

$$J_\varrho = K_\varrho \star J$$

$$\text{where } K_\varrho = \frac{1}{\varrho^2 2\pi} \exp\left(-\frac{x^2 + y^2}{2\varrho^2}\right)$$

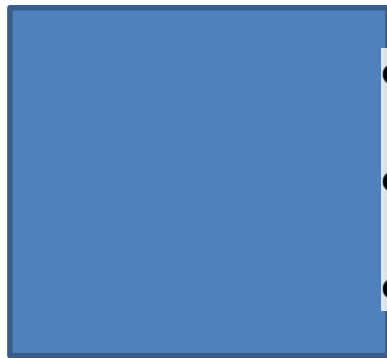
Similar to covariance matrix

Variations of derivatives in a neighborhood

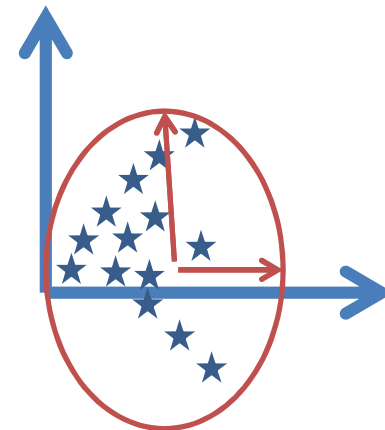
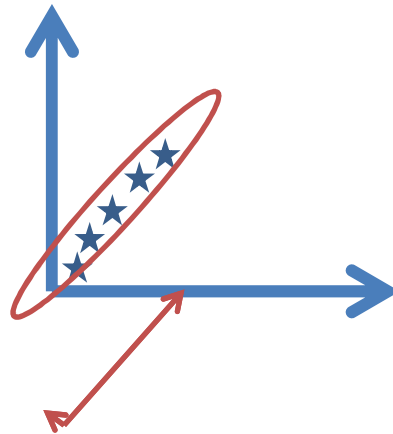
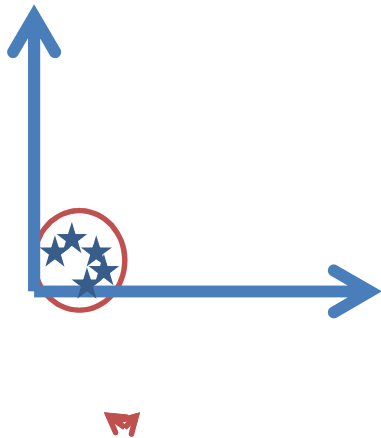
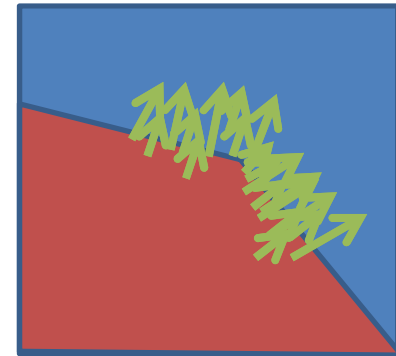
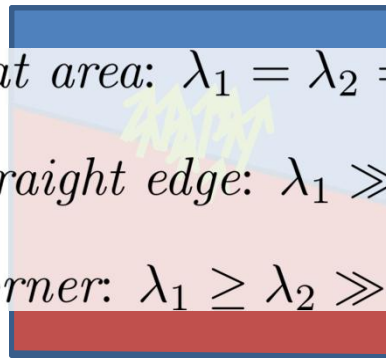


Similar to covariance matrix

Variations of derivatives in a neighborhood



- *flat area*: $\lambda_1 = \lambda_2 = 0$.
- *straight edge*: $\lambda_1 \gg \lambda_2 = 0$.
- *corner*: $\lambda_1 \geq \lambda_2 \gg 0$.



How to compute the structure tensor in practice

- Computation of f_x and f_y

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla f$$

How to compute the structure tensor in practice

- Computation of f_x and f_y

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla f \quad \text{Simply the gradient? But... noise is evil!}$$

How to compute the structure tensor in practice

- Computation of f_x and f_y

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla f \quad \text{Simply the gradient? But... noise is evil!}$$

=> Smooth the image using a gaussian of kernel size σ !

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla K_\sigma \star f$$

How to compute the structure tensor in practice

- Computation of f_x and f_y

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla f \quad \text{Simply the gradient? But... noise is evil!}$$

=> Smooth the image using a gaussian of kernel size σ !

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla K_\sigma \star f \quad \text{But in the lecture slides...}$$

How to compute the structure tensor in practice

- Computation of f_x and f_y

Rule of thumb:

(Always prefer the computation of derivatives in continuous space to differentiation in discrete domain.

=> smooth the image using a gaussian of kernel size σ !

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla K_\sigma \star f \quad \text{But in the lecture slides...}$$

How to compute the structure tensor in practice

- Computation of f_x and f_y

Rule of thumb:

(Always prefer the computation of derivatives in continuous space to differentiation in discrete domain.

=> smooth the image using a gaussian of kernel size σ !

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla K_\sigma \star f \quad \text{But in the lecture slides...}$$

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \begin{pmatrix} \frac{dK_\sigma}{dx} \\ \frac{dK_\sigma}{dy} \end{pmatrix} \star f = (\nabla K_\sigma) \star f$$

How to compute the structure tensor in practice

- Computation of f_x and f_y

Rule of thumb:

(Always prefer the computation of derivatives in continuous space to differentiation in discrete domain.

=> smooth the image using a gaussian of kernel size σ !

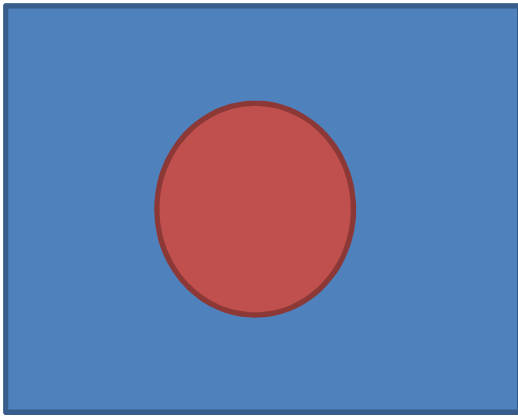
$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \nabla K_\sigma \star f$$

But in the lecture slides...

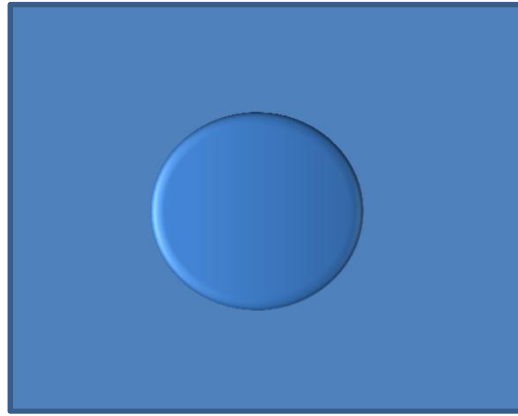
DoGMask

$$\begin{pmatrix} f_x \\ f_y \end{pmatrix} = \begin{pmatrix} \frac{dK_\sigma}{dx} \\ \frac{dK_\sigma}{dy} \end{pmatrix} \star f = (\nabla K_\sigma) \star f$$

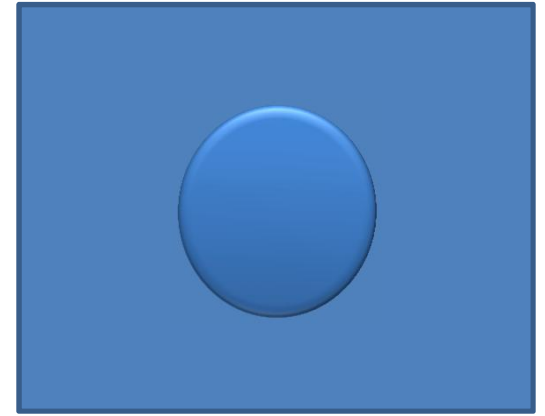
DoGMask'



f

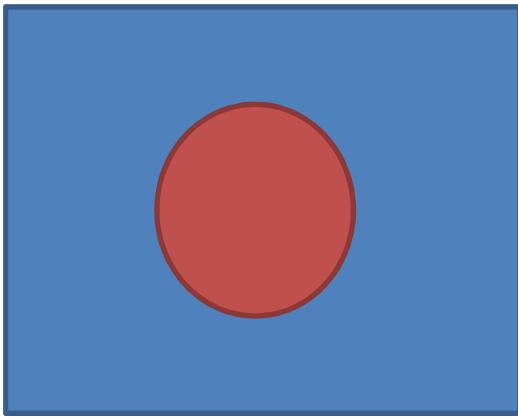


f_x

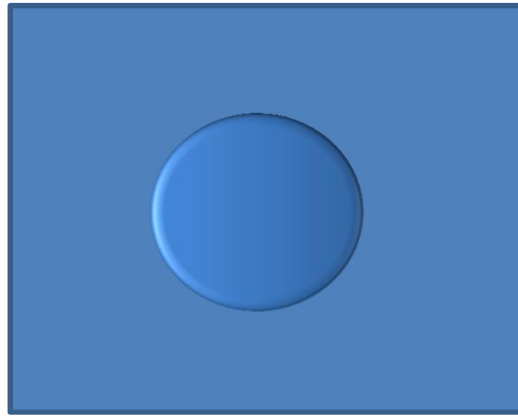


f_y

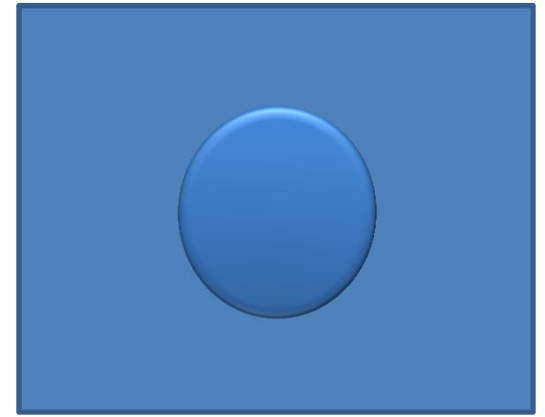
So lets compute $f_x^2, f_x f_y, f_y^2$ by pixel wise multiplication!



f

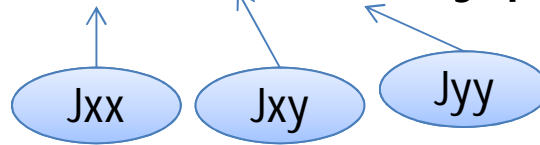


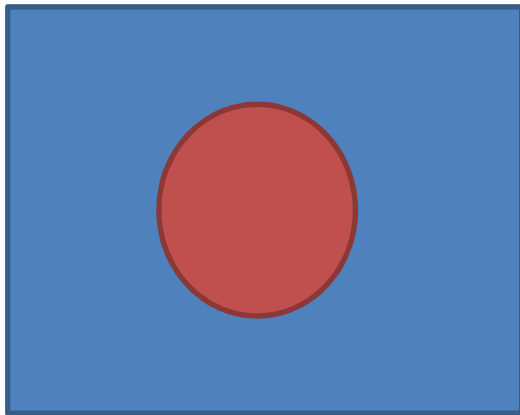
f_x



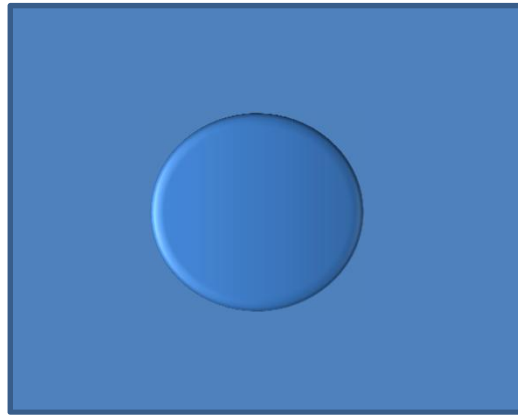
f_y

So lets compute $f_x^2, f_x f_y, f_y^2$ by pixel wise multiplication!

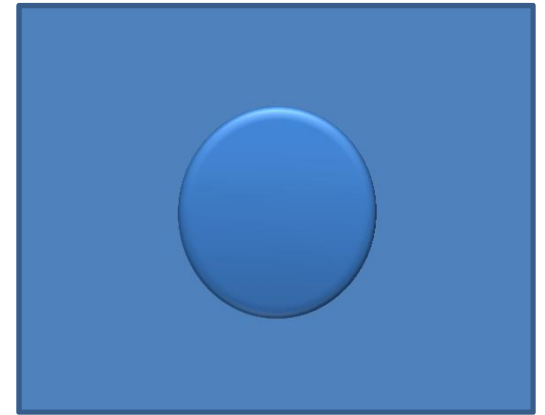




f

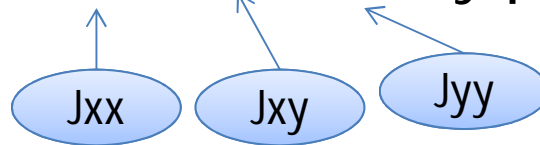


f_x



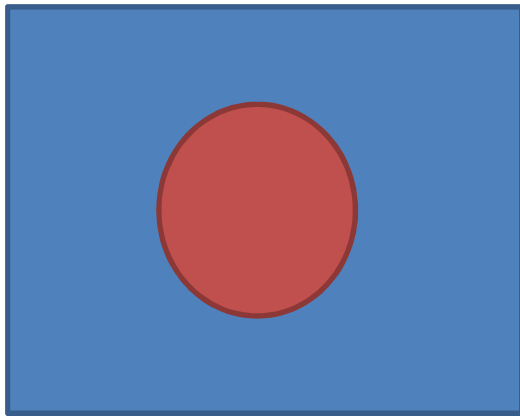
f_y

So lets compute $f_x^2, f_x f_y, f_y^2$ by pixel wise multiplication!

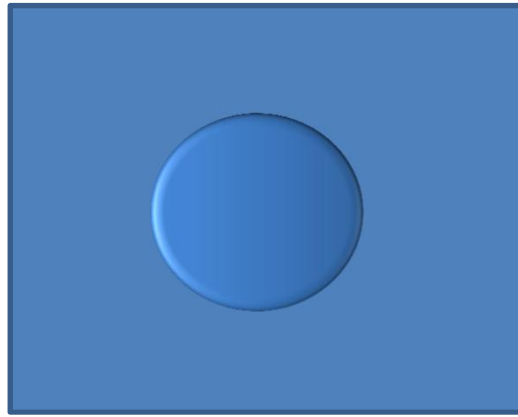


But in the lecture slides...

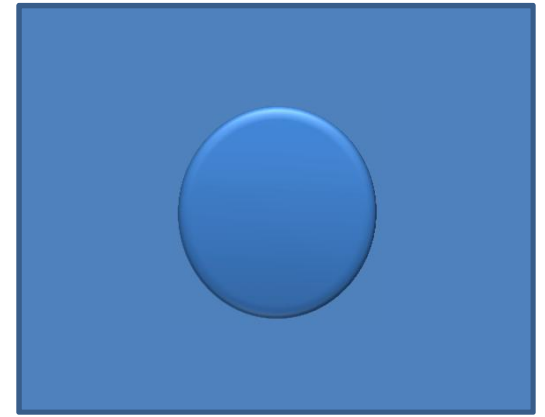
averaging distributes information over neighborhood



f

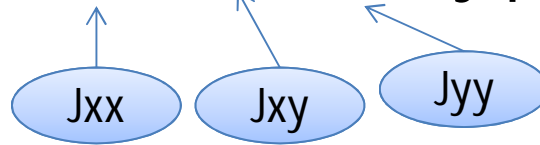


f_x



f_y

So lets compute $f_x^2, f_x f_y, f_y^2$ by pixel wise multiplication!



But in the lecture slides...

averaging distributes information over neighborhood

=> Convolve J_{xx}, J_{xy}, J_{yy} with gaussian filter to obtain Q_{xx}, Q_{xy}, Q_{yy}