Interventional Medical Image Processing (IMIP)

 Exercise 3

 Matthias Hoffmann, Room 10.136
 Matthias.Hoffmann@cs.fau.de

 Yan Xia, Room 09.157
 yan.xia@cs.fau.de

Vesselness Filtering, Bilateral Filter

## 1 Vesselness Filtering

In this task we will perform multi scale vessel enhancement filtering [1] to segment the vessels in a retinal fundus image. Changes in the vessel topology and shape can be indicative of retinal disease such as diabetic retinopathy. Download the files "vesselness\_ex.m" and the provided images from the exercise material page. Complete the MATLAB script to implement fully functional automatic vessel segmentation. [1] and the script from the lecture provide the neccessary details and equations.

Figure 1: Color fundus image (left) and a corresponding manual vessel segmentation (right)

2 - 1

This consists of the following steps:

- 1. Loading of the fundus image and the associated mask image
- 2. Extraction of the green color channel, thresholding, intensity inversion
- 3. Multi-scale vessel enhancement filtering including:





 $\mathrm{SS}~2014$ 

- (a) Smoothing the image using a Gaussian with successively larger  $\sigma$
- (b) Computation of the second derivatives
- (c) Finding the Eigenvalues of the Hessian matrix at every pixel
- (d) Calculate the two parts of the Vesselness equation  $R_b$  and S
- (e) Calculate the vesselness value itself
- (f) Combining the vesselness values from the different scales by use of the maximum
- 4. Thresholding the vesselness image to generate a binary image

## 2 Bilateral Filter

The bilateral filter[2] is an edge-preserving filter. It takes not only the spacial distance to a neighbor pixel into account but considers also the similarity of neighboring pixels. In theory, all pixels of the image contribute to the value of a filtered pixel (see lecture script). We consider only a neighborhood of size  $2 \cdot n + 1$  around a pixel (x, y). So the formula for the filter can be rewritten to:

$$\vec{h}(x,y) = \frac{\sum_{\xi=-n}^{+n} \sum_{\nu=-n}^{+n} f(x-\xi, y-\nu) \cdot c(x,y,\xi,\nu) \cdot s(x,y,\xi,\nu)}{k(x,y)}$$

k is a normalization defined by

$$k(x,y,) = \sum_{\xi=-n}^{+n} \sum_{\upsilon=-n}^{+n} c(x,y,\xi,\upsilon) \cdot s(x,y,\xi,\upsilon)$$

- Download the MATLAB files "bilateral.m" and "bilateralFilter.m" as well as an image, for example a picture of the computerscience tower: http://www.informatik.uni-erlangen.de/img/hochhaus.jpg
- The closeness c is already given as the distance weighted by a gaussian with  $\sigma_C$ .
- Use as similarity measure s the intensity difference weighted by a gaussian with  $\sigma_S$ .
- Optional: Extend the bilateral filter to color images. Use as similarity measure the norm  $|| \cdot ||_2$  of the color difference weighted by a gaussian.

## **3** References

- "Multiscale vessel enhancement filtering", Alejandro F. Frangi, Wiro J. Niessen, Koen L. Vincken, Max A. Viergever, 1998
- 2. "Bilateral Filtering, for Gray and Color Images", Tomasi, Roberto Manduchi 1998

## 4 Useful MATLAB commands

eig, gradient, fspecial, imfilter, im2bw

We will work interactively on the implementation of the above mentioned tasks!