# **DMIP - Exercise:**

Defect Pixel Interpolation

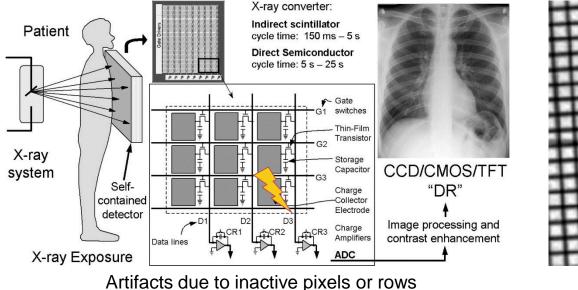
Bastian Bier, Marco Bögel Pattern Recognition Lab (CS 5)





#### **Defect Pixels in Flat Panel Detectors**

- Defect pixels are caused by defect detector cells.
- Small detectors are composed to generate a large one, which leads to butting cross effects.



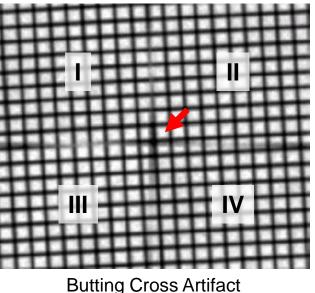


Image taken from: Samei E et al. Radiographics 2004;24:313-334

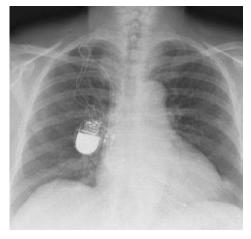


#### **Defect Pixels in Flat Panel Detectors**

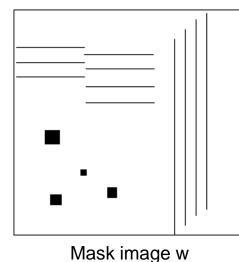
- Let f<sub>i,i</sub> denote the intensity value at grid point (i,j) of the ideal image f that has no defect pixels.
- Let w<sub>i,j</sub> denote the indicator value at (i,j) where w is **mask image** that indicates defect and uncorrupted pixels:

$$w_{i,j} = \left\{ egin{array}{cc} 0 & ext{if pixel is defect} \ 1 & ext{otherwise} \end{array} 
ight.$$

• Let g<sub>i,j</sub> denote the intensity value at grid point (i,j) of the **observed image** g that is acquired with the flat panel detector that has defect pixels.



Ideal image f



Observed image g

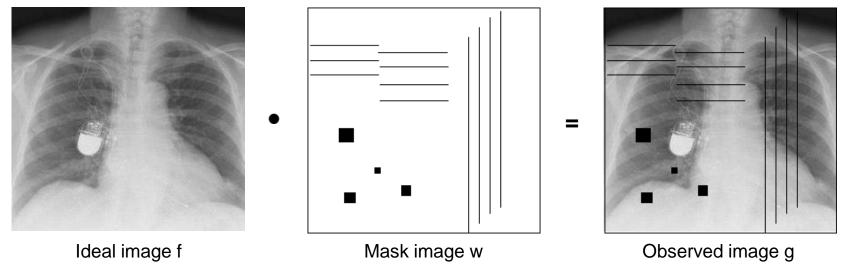


#### **Defect Pixels in Flat Panel Detectors**

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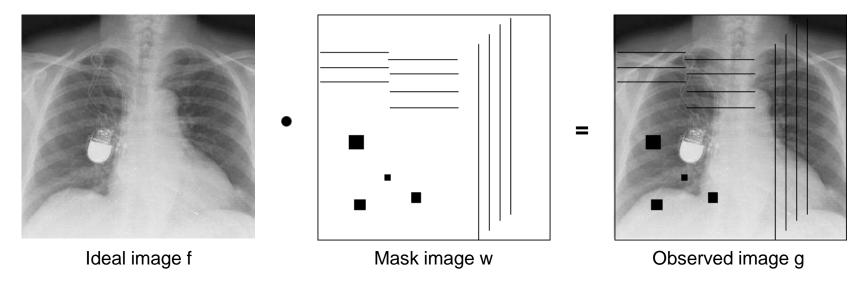
• Let g<sub>i,j</sub> denote the intensity value at grid point (i,j) of the **observed image** g that is acquired with the flat panel detector that has defect pixels.



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#### **Defect Pixels in Flat Panel Detectors**



- Defect pixel problem:  $f(n) \cdot w(n) = g(n)$
- Goal: Find f(n), given the observed image g(n) and the defect mask w(n)



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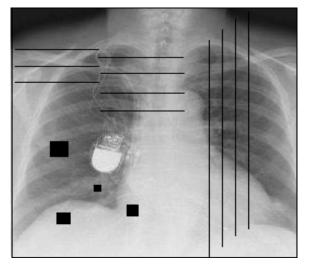


#### **Problem Statement**

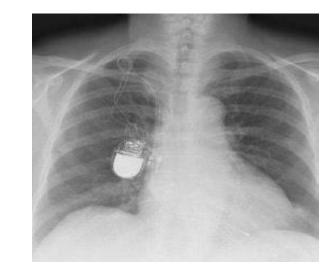
- Restore the ideal image based on the observed image and the known defect pixel mask.
- Defect pixel correction:
  - Spatial Domain: Interpolation
  - Frequency Domain: Band Limitation
  - Frequency Domain:



: Iterative Deconvolution



Observed image g



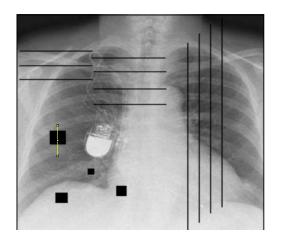
Ideal image f

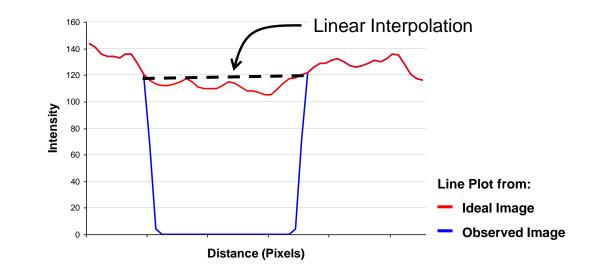


#### **Defect Pixel Correction by Spatial Interpolation**

- Interpolate between active pixels to recover the inactive ones:
  - Bilinear interpolation
  - Median

#### However, this is only suitable for small defect areas!







#### **Fourier Transform Revisited**

- Convolution theorem
- Symmetry property of Fourier transform of real signals



#### **Fourier Transform Revisited**

• Convolution theorem  

$$FT(f \star h)(\xi) = \sum_{n=0}^{N-1} \sum_{k=0}^{N-1} f(k)h(n-k)e^{\frac{-2\pi i n\xi}{N}}$$

$$= \sum_{k=0}^{N-1} f(k) \sum_{n=0}^{N-1} h(n-k)e^{\frac{-2\pi i n\xi}{N}}$$

$$= \sum_{k=0}^{N-1} f(k)e^{\frac{-2\pi i k\xi}{N}}H(\xi) = F(\xi)H(\xi) = G(\xi)$$

The **convolution** of two signals in the **time domain**, corresponds to a **multiplication** in the **frequency domain**.

• Symmetry property of Fourier transform of real signals



#### **Fourier Transform Revisited**

- Convolution theorem
- Symmetry property of Fourier transform of real signals
   If f(n) is a real valued discrete signal of length N, the Fourier transform F(ξ) fulfills the symmetry property:

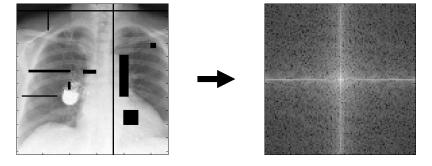
$$F(\xi) = F^*(N - \xi)$$

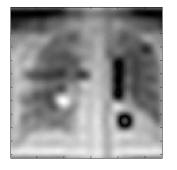
where "\* " denotes the conjugate complex.

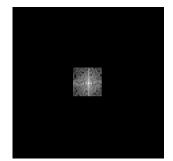


#### **Iterative Band Limitation**

- **1. Fourier transform**
- 2. Cut off high frequencies
- 3. Inverse Fourier transform
- 4. Replace only defect areas
- 5. Repeat from 1.



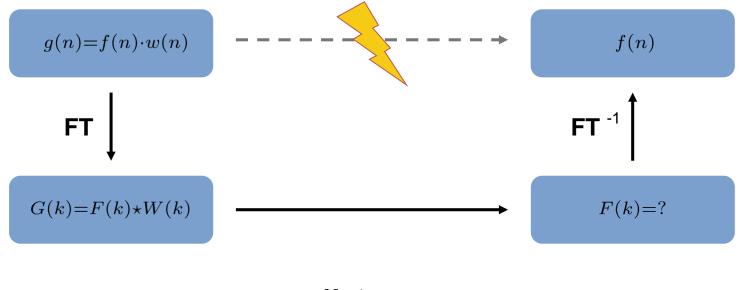






#### **Defect Pixel Correction by Symmetry Properties**

• Application of Fourier convolution theorem:



$$G(k) = \frac{1}{N}F(k) \star W(k) = \frac{1}{N}\sum_{l=0}^{N-1}F(l) \cdot W(k-l), \qquad 0 \le n, k < N$$



#### **Defect Pixel Correction by Symmetry Properties**

- Application of Fourier symmetry properties:
- Use Dirac's  $\delta$ -function to select a line pair F(s) and F(N-s):

$$\hat{F}(k) = \hat{F}(s)\delta(k-s) + \hat{F}(N-s)\delta(k-N+s)$$

where  $\hat{F}$  denotes an estimate of F, and  $\delta$  - function is defined by:

$$\delta(n) = \begin{cases} 1 & \text{if } n = 0\\ 0 & \text{otherwise} \end{cases}$$

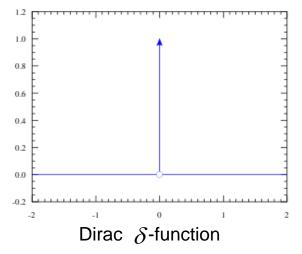


Image taken from: Wikipedia



#### **Defect Pixel Correction by Symmetry Properties**

• After frequency selection, we convolve with the mask

$$\hat{G}(k) = \frac{1}{N}\hat{F}(k) \star W(k) = \frac{1}{N}\sum_{l=0}^{N-1}\hat{F}(l) \cdot W(k-l)$$



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$$\hat{F}(l)$$
 is only non-zero if  $\ l=s \ ee \ l=N-s$ 



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$$\hat{G}(k) = \frac{1}{N} \left( \hat{F}(s) W(k-s) + \hat{F}(N-s) W(k-(N-s)) \right)$$



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$$\hat{G}(k) = \frac{1}{N} \left( \hat{F}(s)W(k-s) + \hat{F}(N-s)W(k-(N-s)) \right)$$
$$= \hat{F}^*(s)$$



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$$\hat{G}(s) = \frac{1}{N} \left( \hat{F}(s) W(0) + \hat{F}^*(s) W(2s - N) \right)$$



#### **Defect Pixel Correction by Symmetry Properties**

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#### **Defect Pixel Correction by Symmetry Properties**

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$$\hat{G}(s) = \frac{1}{N} \left( \hat{F}(s) W(0) + \hat{F}^*(s) W(2s) \right)$$



#### **Defect Pixel Correction by Symmetry Properties**

• Application of Fourier symmetry properties:

Select a line pair G(s) and G(N-s) of the Fourier transform of the observed image. The observed image is described by a convolution of the ideal image and the known defect pixel mask:

$$G(s) = \frac{1}{N} \left( \hat{F}(s) W(0) + \hat{F}^*(s) W(2s) \right)$$

• And for the conjugate complex:

$$G^*(s) = \frac{1}{N} \left( \hat{F}^*(s) W^*(0) + \hat{F}(s) W^*(2s) \right)$$

• Using these two equations, we can compute:

$$\hat{F}(s) = N \frac{G(s)W^*(0) - G^*(s)W(2s)}{|W(0)|^2 - |W(2s)|^2}$$



#### **Defect Pixel Correction by Symmetry Properties**

• Special case without symmetry property (for s=0 and s = N/2)

$$G(s) = \frac{1}{N} \left( \hat{F}(s)W(0) + \hat{F}^*(s)W(2s) \right)$$
$$G^*(s) = \frac{1}{N} \left( \hat{F}^*(s)W^*(0) + \hat{F}(s)W^*(2s) \right)$$



#### **Defect Pixel Correction by Symmetry Properties**

• Special case without symmetry property (for s=0 and s = N/2)

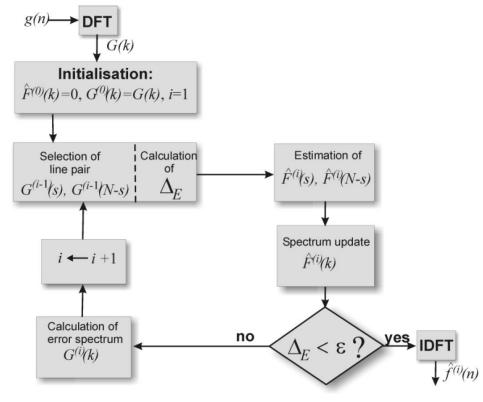
$$G(s) = \frac{1}{N} \left( \hat{F}(s)W(0) + \hat{F}^*(s)W(2s) \right)$$
$$G^*(s) = \frac{1}{N} \left( \hat{F}^*(s)W^*(0) + \hat{F}(s)W^*(2s) \right)$$
$$\hat{F}(s) = N \left( \frac{G(s)}{W(0)} \right)$$



#### **Defect Pixel Correction by Symmetry Properties**

So far only correction at line pair



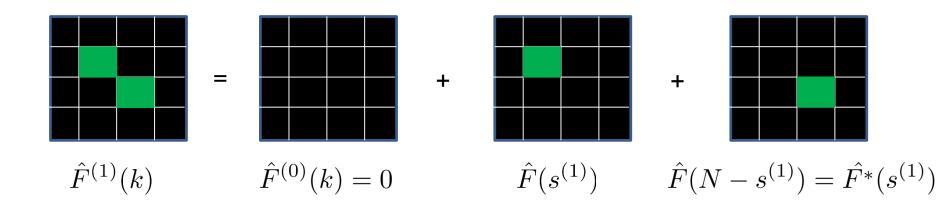


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#### **Defect Pixel Correction by Symmetry Properties**

- So far we only found estimates for a single or a pair of selected lines
- We also need to update the global estimate of the spectrum after each linepair computation





#### **Defect Pixel Correction by Symmetry Properties**

• How can we update the error spectrum G?

$$G^{(i)}(k) = G^{(i-1)}(k) - \hat{G}(k) = G^{(i-1)}(k) - \frac{1}{N} \left( \hat{F}(k) * W(k) \right)$$



#### **Defect Pixel Correction by Symmetry Properties**

• How can we update the error spectrum G?

$$G^{(i)}(k) = G^{(i-1)}(k) - \hat{G}(k) = G^{(i-1)}(k) - \frac{1}{N} \left( \hat{F}(k) * W(k) \right)$$

- Just subtract the new estimate from the previous estimate
- Requires convolution!!!  $\rightarrow$  Same complexity as FFT?
- F(k) changed only at two positions  $\rightarrow$  Convolution much easier to compute



#### **Defect Pixel Correction by Symmetry Properties**

- How to select the line pairs each iteration?
- Just select the maximum of the error spectrum

$$s^{(i)} = \operatorname*{argmax}_{\hat{s}^{(i)}} G^{(i)}(\hat{s}^{(i)})$$

- Detailed derivation can be found in the paper.
- It is based on Parseval's theorem.
- Approach minimizes the mean square error (MSE) in valid areas:

MSE = 
$$\sum_{n=0}^{N} (g(n) - \hat{f}(n)w(n))^2$$